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**Riemann sum - Wikipedia**

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In linear algebra, a rotation matrix is a matrix that is used to perform a rotation in Euclidean space. For example, using the convention below, the matrix  $R = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$  rotates points in the xy-plane counterclockwise through an angle  $\theta$ , about the origin of the Cartesian coordinate system. To perform the rotation using a rotation matrix  $R$ , the position of each point must be represented ...

**Rotation matrix - Wikipedia**

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